Subcell *a posteriori* limitation for DG scheme through flux reconstruction

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- Introduction
- DG as a subcell finite volume
- A posteriori subcell limitation
- Mumerical results

1D scalar conservation law

•
$$\frac{\partial u}{\partial t} + \frac{\partial F(u)}{\partial x} = 0, \quad (x, t) \in \omega \times [0, T]$$

•
$$u(x,0) = u_0(x), \qquad x \in \omega$$

$(k+1)^{th}$ order discretization

- $\{\omega_i\}_i$ a partition of ω , such that $\omega_i = [x_{i-\frac{1}{2}}, x_{i+\frac{1}{2}}]$
- $0 = t^0 < t^1 < \cdots < t^N = T$ a partition of the temporal domain [0, T]
- $u_h(x,t)$ the numerical solution, such that $u_{h|\omega_i} = u_h^i \in \mathbb{P}^k(\omega_i)$

$$u_h^i(x,t) = \sum_{m=1}^{K+1} u_m^i(t) \, \sigma_m(x)$$

Local variational formulation on ω_i

$$\bullet \int_{\omega_i} \frac{\partial u_h^i}{\partial t} \psi \, \mathrm{d}x = \int_{\omega_i} F(u_h^i) \frac{\partial \psi}{\partial x} \, \mathrm{d}x - \left[\mathcal{F} \psi \right]_{x_{i-\frac{1}{2}}}^{x_{i+\frac{1}{2}}}, \qquad \forall \psi \in \mathbb{P}^k(\omega_i)$$

•
$$\mathcal{F}_{i+\frac{1}{2}} = \mathcal{F}\left(u_h^i(x_{i+\frac{1}{2}},t), u_h^{i+1}(x_{i+\frac{1}{2}},t)\right)$$

numerical flux

Subcell resolution of DG scheme

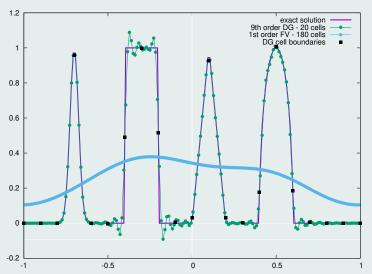


Figure: Linear advection of composite signal after 4 periods

Gibbs phenomenon

- High-order schemes leads to spurious oscillations near discontinuities
- Leads potentially to nonlinear instability, non-admissible solution, crash
- Vast literature of how prevent this phenomenon to happen:
 - a priori and a posteriori limitations

A priori limitation

- Artificial viscosity
- Flux limitation
- Slope/moment limiter
- Hierarchical limiter
- ENO/WENO limiter

A posteriori limitation

- MOOD ("Multi-dimensional Optimal Order Detection")
- Subcell finite volume limitation
- Subcell limitation through flux reconstruction

Admissible numerical solution

- Maximum principle / positivity preserving
- Prevent the code from crashing (for instance avoiding NaN)
- Ensure the conservation of the scheme

Spurious oscillations

- Discrete maximum principle
- Relaxing condition for smooth extrema

Accuracy

- Retain as much as possible the subcell resolution of the DG scheme
- Minimize the number of subcell solutions to recompute



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DG as a subcell finite volume

- Rewrite DG scheme as a specific finite volume scheme on subcells
- Exhibit the corresponding subcell numerical fluxes: reconstructed flux

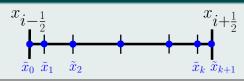
Local variational formulation

$$\bullet \int_{\omega_i} \frac{\partial u_h^i}{\partial t} \psi \, \mathrm{d}x = \int_{\omega_i} F(u_h^i) \frac{\partial \psi}{\partial x} \, \mathrm{d}x - \left[\mathcal{F} \psi \right]_{x_{i-\frac{1}{2}}}^{x_{i+\frac{1}{2}}}, \qquad \forall \psi \in \mathbb{P}^k(\omega_i)$$

• Substitute $F(u_h^i)$ with $F_h^i \in \mathbb{P}^{k+1}(\omega_i)$ (collocated or L_2 projection)

$$\bullet \int_{\omega_i} \frac{\partial u_h^i}{\partial t} \psi \, \mathrm{d}x = - \int_{\omega_i} \frac{\partial F_h^i}{\partial x} \psi \, \mathrm{d}x + \left[\left(F_h^i - \mathcal{F} \right) \psi \right]_{x_{i-\frac{1}{2}}}^{x_{i+\frac{1}{2}}}, \qquad \forall \psi \in \mathbb{P}^k(\omega_i)$$

Subcell decomposition through k + 2 flux points



Subresolution basis functions

- ω_i is subdivided in k+1 subcells $S_m^i = [\widetilde{x}_{m-1}, \widetilde{x}_m]$
- Let us introduce the k+1 basis functions $\{\phi_m\}_m$ such that $\forall\,\psi\in\mathbb{P}^k(\omega_i)$

$$\int_{\omega_i} \phi_m \, \psi \, \mathrm{d} x = \int_{S_m^i} \psi \, \mathrm{d} x, \qquad \forall \, m = 1, \dots, k+1$$

• Let us define $\overline{\psi}_m = \frac{1}{|S_m^i|} \int_{S_m^i} \psi \, \mathrm{d}x$ the subcell mean value

Local variational formulation

$$\bullet \int_{\omega_i} \frac{\partial u_h^i}{\partial t} \phi_m \, \mathrm{d}x = -\int_{\omega_i} \frac{\partial F_h^i}{\partial x} \phi_m \, \mathrm{d}x + \left[(F_h^i - \mathcal{F}) \phi_m \right]_{x_{i-\frac{1}{2}}}^{x_{i+\frac{1}{2}}}$$

$$\bullet \ \frac{\partial \, \overline{u}_{m}^{i}}{\partial t} = -\frac{1}{|\mathcal{S}_{m}^{i}|} \left(\left[F_{h}^{i} \right]_{\widetilde{x}_{m-1}}^{\widetilde{x}_{m}} - \left[\phi_{m} \left(F_{h}^{i} - \mathcal{F} \right) \right]_{x_{i-\frac{1}{2}}}^{x_{i+\frac{1}{2}}} \right)$$

$$\bullet \ \frac{\partial \, \overline{u}_{m}^{i}}{\partial t} = -\frac{1}{|S_{m}^{i}|} \left(\widehat{F}_{m}^{i} - \widehat{F}_{m-1}^{i} \right)$$

Subcell finite volume

Linear system

$$\bullet \ \widehat{F}_{m}^{i} - \widehat{F}_{m-1}^{i} = \left[F_{h}^{i}\right]_{\widetilde{X}_{m-1}}^{\widetilde{X}_{m}} - \left[\phi_{m} \left(F_{h}^{i} - \mathcal{F}\right)\right]_{X_{i-\frac{1}{2}}}^{X_{i+\frac{1}{2}}}, \qquad \forall m = 1, \dots, k$$

• $\widehat{F}_0^i = \mathcal{F}_{i-\frac{1}{2}}$ and $\widehat{F}_{k+1}^i = \mathcal{F}_{i+\frac{1}{2}}$

Reconstructed flux

$$\bullet \ \widehat{F}_{m}^{i} = F_{h}^{i}(\widetilde{x}_{m}) - C_{i-\frac{1}{2}}^{(m)} \left(F_{h}^{i}(x_{i-\frac{1}{2}}) - \mathcal{F}_{i-\frac{1}{2}}\right) - C_{i+\frac{1}{2}}^{(m)} \left(F_{h}^{i}(x_{i+\frac{1}{2}}) - \mathcal{F}_{i+\frac{1}{2}}\right)$$

•
$$C_{i-\frac{1}{2}}^{(m)} = \sum_{p=m+1}^{k+1} \phi_p(x_{i-\frac{1}{2}})$$
 and $C_{i+\frac{1}{2}}^{(m)} = \sum_{p=1}^m \phi_p(x_{i+\frac{1}{2}})$

Correction terms for symmetric distribution of $\{\widetilde{x}_m\}_m$

• Let
$$\mathbf{B} \in \mathbb{R}^{k+1}$$
 be defined as $B_j = (-1)^{j+1} \frac{(k+1)(k+j)!}{(j!)^2(k+1-j)!}$

•
$$\widetilde{\xi}_m = \frac{\widetilde{x}_m - X_{i-\frac{1}{2}}}{X_{i+\frac{1}{n}} - X_{i-\frac{1}{n}}}, \quad \forall \ m = 0, \dots, k+1$$

•
$$C_{i-\frac{1}{2}}^{(m)} = 1 - \left(\widetilde{\xi}_m, \dots, (\widetilde{\xi}_m)^{k+1}\right)^t \cdot \mathbf{B}$$
 and $C_{i+\frac{1}{2}}^{(m)} = C_{i-\frac{1}{2}}^{(k+1-m)}$

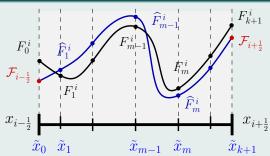
Subcell finite volume equivalent to DG

$$\bullet \ \frac{\partial \, \overline{u}_{m}^{i}}{\partial t} = -\frac{1}{|S_{m}^{i}|} \left(\widehat{F}_{m}^{i} - \widehat{F}_{m-1}^{i} \right),$$

$$\forall m=1,\ldots,k+1$$

$$\bullet \ \widehat{F}_{m}^{i} = F_{h}^{i}(\widetilde{x}_{m}) - C_{i-\frac{1}{2}}^{(m)} \left(F_{h}^{i}(x_{i-\frac{1}{2}}) - \mathcal{F}_{i-\frac{1}{2}} \right) - C_{i+\frac{1}{2}}^{(m)} \left(F_{h}^{i}(x_{i+\frac{1}{2}}) - \mathcal{F}_{i+\frac{1}{2}} \right)$$

Reconstructed flux taking into account flux jumps



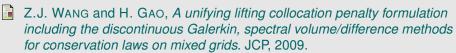
Flux reconstruction / CPR

The correction functions defined as

$$g_{LB}(x) = \sum_{m=0}^{k+1} C_{i-\frac{1}{2}}^{(m)} L_m(x)$$
 and $g_{RB}(x) = \sum_{m=0}^{k+1} C_{i+\frac{1}{2}}^{(m)} L_m(x)$

are nothing but the right and left Radau \mathbb{P}^k polynomials





Subcell finite volume

- Reconstructed flux is used as a numerical flux for subcell FV schemes
- This demonstration is not restricted to the flux collocation case
- The correction terms are very simple and explicitly defined

- A posteriori subcell limitation



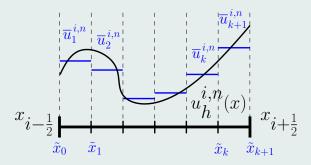
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Projection on subcells of RKDG solution

- $u_h^i = \sum_{m=1}^{k+1} u_m^i \sigma_m$ is uniquely defined by its k+1 submean values
- Introducing the matrix Π defined as $\pi_{mp} = \frac{1}{|S_m^i|} \int_{S_n^i} \sigma_p \, \mathrm{d}x$, then

$$\Pi\left(u_1^{i,n},\ldots,u_{k+1}^{i,n}\right)^{\mathsf{t}}=\left(\overline{u}_1^{i,n},\ldots,\overline{u}_{k+1}^{i,n}\right)^{\mathsf{t}}$$

Polynomial solution and its associated submean values



Set up

- We assume that, for each cell, the $\{\overline{u}_m^{i,n}\}_m$ are admissible
- Compute a candidate solution u_h^{n+1} from u_h^n through unlimited DG
- \bullet For each subcell, check if the submean values $\,\{\overline{u}_m^{\,i,n+1}\}_m\,$ are ok

Physical admissibility detection (PAD)

- Check if $\overline{u}_m^{i,n+1}$ lies in an convex physical admissible set (maximum principle for SCL, positivity of the pressure and density for Euler, . . .)
- Check if there is any NaN values

Numerical admissibility detection (NAD)

Discrete maximum principle DMP on submean values:

$$\min_{p}(\overline{u}_p^{i-1,n},\overline{u}_p^{i,n},\overline{u}_p^{i+1,n}) \leq \overline{u}_m^{i,n+1} \leq \max_{p}(\overline{u}_p^{i-1,n},\overline{u}_p^{i,n},\overline{u}_p^{i+1,n})$$

This criterion needs to be relaxed to preserve smooth extrema

Limited reconstructed flux

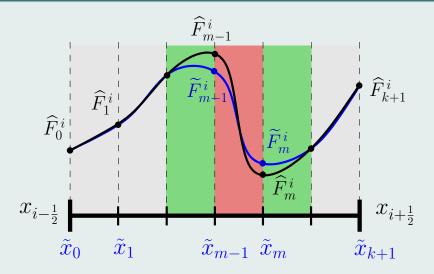


Figure: Correction of the reconstructed flux

Flowchart

- Project $u_h^{i,n+1}$ to get the submean values $\overline{u}_m^{i,n+1}$
- ullet Check $\overline{u}_m^{i,n+1}$ through PAD and NAD
- $\ \, \ \,$ If $\overline{u}_m^{i,n+1}$ is admissible go further in time, otherwise modify the corresponding reconstructed flux values

$$\widetilde{F}_{m-1}^i = \mathcal{F}(\overline{u}_{m-1}^{i,n}, \overline{u}_m^{i,n}) \quad \text{and} \quad \widetilde{F}_m^i = \mathcal{F}(\overline{u}_m^{i,n}, \overline{u}_{m+1}^{i,n})$$

- Through the corrected reconstructed flux, recompute the submean values for tagged subcells and their first neighbors
- Return to point 2

Conclusion

- The limitation only affects the DG solution at the subcell scale
- The limited scheme is conservative at the subcell level
- In practice, few submean values need to be recomputed



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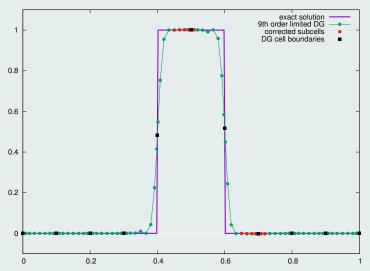


Figure: 9th order limited DG: NAD criterion

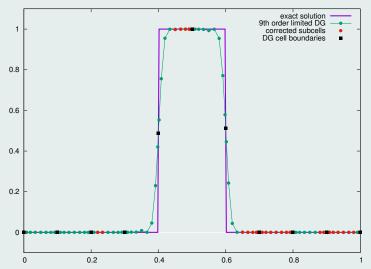


Figure: 9th order limited DG on 10 cells: NAD and PAD criteria

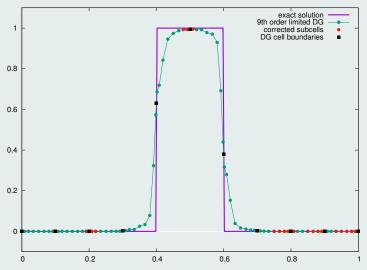


Figure: 9th order limited DG on 10 cells: subcell DMP

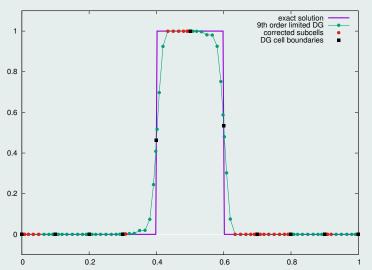


Figure: 9th order limited DG on 10 cells: subcell DMP + 2nd order correction

Linear advection of a composite signal after 4 periods

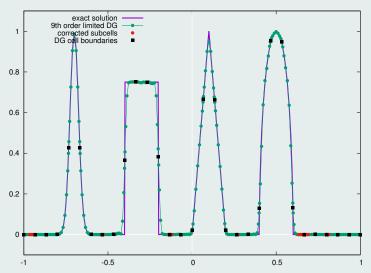


Figure: 9th order limited DG after 4 periods on 30 cells

Linear advection of a composite signal after 4 periods

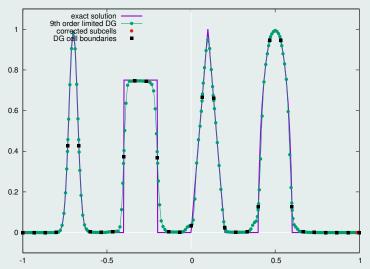


Figure: 9th order limited DG after 4 periods on 30 cells: subcell DMP

Linear advection of a composite signal after 4 periods

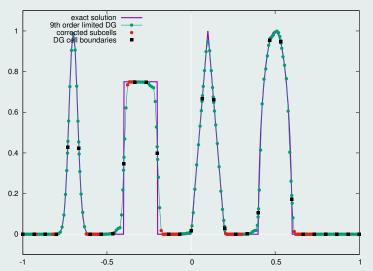


Figure: 9th order limited DG after 4 periods on 30 cells: subcell DMP + 2nd order correction

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Burgers equation: $u_0(x) = \sin(2\pi x)$

Figure : 9th order limited DG on 10 cells for $t_f = 0.7$

Burgers equation: expansion and shock waves collision

Figure : 9th order limited DG on 15 cells for $t_f = 1.2$

2D grid and subgrid

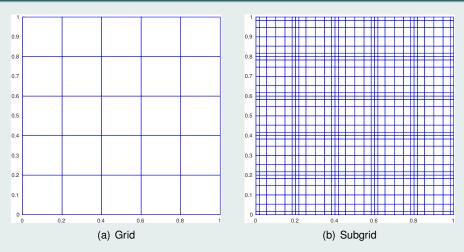


Figure: 5x5 Cartesian grid and corresponding subgrid for a 6th order DG scheme

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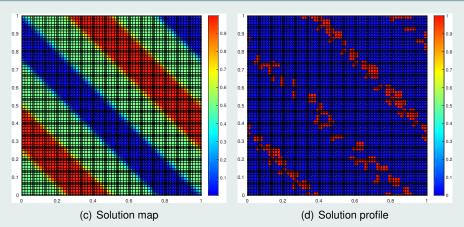


Figure: 6th order limited DG on a 15x15 Cartesian mesh

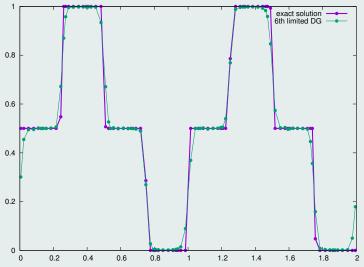


Figure: 6th order limited DG on a 15x15 Cartesian mesh

Rotation of a composite signal after 1 period

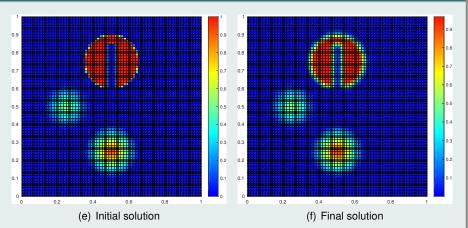


Figure: 6th order limited DG on a 15x15 Cartesian mesh

Rotation of a composite signal after 1 period

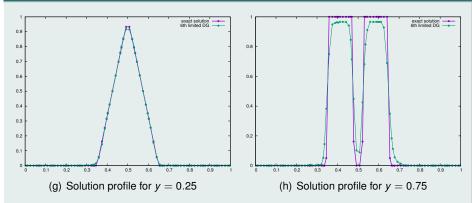


Figure: 6th order limited DG on a 15x15 Cartesian mesh

Rotation of a composite signal after 1 period: x = 0.25

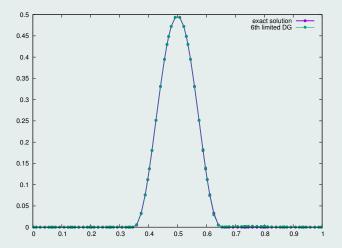


Figure: 6th order limited DG on a 15x15 Cartesian mesh

Burgers equation with $u_0(x, y) = \sin(2\pi (x + y))$

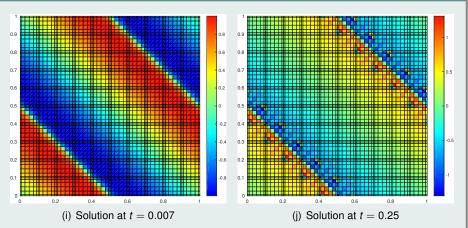


Figure: 6th order unlimited DG on a 10x10 Cartesian mesh



Burgers equation with $u_0(x, y) = \sin(2\pi (x + y))$

(k) Solution map

(I) Detected subcells

Figure : 6th order limited DG on a 10x10 Cartesian mesh until t = 0.5

Burgers equation with $u_0(x, y) = \sin(2\pi (x + y))$ at t = 0.5

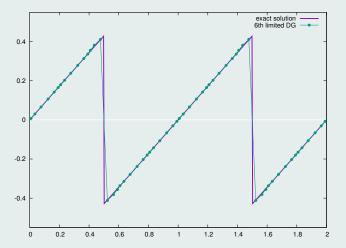


Figure: 6th order limited DG density profile on a 10x10 Cartesian mesh

Burgers equation with composite signal

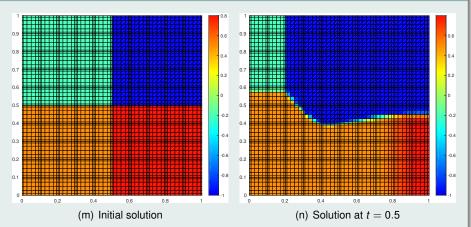


Figure: 6th order limited DG on a 10x10 Cartesian mesh

Sod shock tube problem

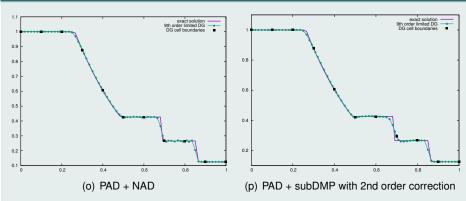


Figure: 9th order limited DG on 10 cells

Hell shock tube problem

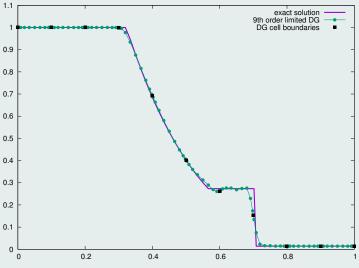


Figure: 9th order limited DG on 10 cells

Shock acoustic-wave interaction problem

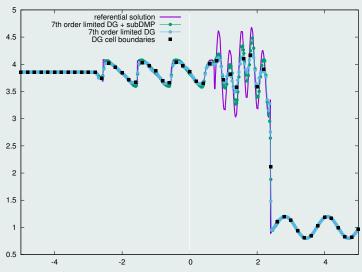


Figure: 7th order limited DG on 50 cells

Shock acoustic-wave interaction problem

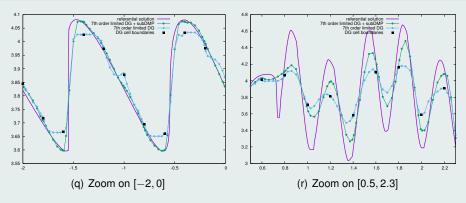


Figure: 7th order limited DG on 50 cells

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Article in preparation



F. VILAR, A Posteriori Correction of High-Order Discontinuous Galerkin Scheme through Subcell Finite Volume Formulation and Flux Reconstruction. JCP, 2018.

High-order Lagrangian hydrodynamics

- - F. VILAR, C.-W. SHU AND P.-H. MAIRE, *Positivity-preserving* cell-centered Lagrangian schemes for multi-material compressible flows: Form first-order to high-orders. Part II: The 2D case. JCP, 2016.
- F. VILAR, C.-W. SHU AND P.-H. MAIRE, *Positivity-preserving* cell-centered Lagrangian schemes for multi-material compressible flows: Form first-order to high-orders. Part I: The 1D case. JCP, 2016.
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- F. VILAR, C.-W. SHU AND P.-H. MAIRE, *Positivity-preserving* cell-centered Lagrangian schemes for multi-material compressible flows: Form first-order to high-orders. Part I: The 1D case. JCP, 2016.
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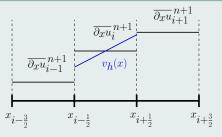
Relaxation of the DMP

- $V_{\min \backslash \max} = \min \backslash \max(\overline{\partial_X u_i^{n+1}}, \overline{\partial_X u_{i-1}^{n+1}})$
- If $(v_L > \overline{\partial_x u_i}^{n+1})$ Then $\alpha_L = \min(1, \frac{v_{\max} \overline{\partial_x u_i}^{n+1}}{v_R \overline{\partial_x u_i}^{n+1}})$
- If $(v_L < \overline{\partial_x u_i}^{n+1})$ Then $\alpha_L = \min(1, \frac{v_{\min} \overline{\partial_x u_i}^{n+1}}{v_R \overline{\partial_x u_i}^{n+1}})$
- $V_R = \overline{\partial_x u_i}^{n+1} + \frac{\Delta x_i}{2} \overline{\partial_{xx} u_i}^{n+1}$
- $V_{\min \backslash \max} = \min \backslash \max(\overline{\partial_x u_i}^{n+1}, \overline{\partial_x u_{i+1}}^{n+1})$
- If $(v_R > \overline{\partial_x u_i}^{n+1})$ Then $\alpha_R = \min(1, \frac{v_{\max} \overline{\partial_x u_i}^{n+1}}{v_R \overline{\partial_x u_i}^{n+1}})$
- If $(v_R < \overline{\partial_x u_i}^{n+1})$ Then $\alpha_R = \min(1, \frac{v_{\min} \overline{\partial_x u_i}^{n+1}}{v_R \overline{\partial_x u_i}^{n+1}})$

Relaxation of the DMP

- If $(\alpha = 1)$ Then DMP is relaxed

Hierarchical limiter



- $v_h(x) = \overline{\partial_x u_i}^{n+1} + (x x_i) \overline{\partial_{xx} u_i}^{n+1}$
- M. YANG and Z.J. WANG, A parameter-free generalized moment limiter for high-order methods on unstructured grids. AAMM., 2009.
- D. Kuzmin, A vertex-based hierarchical slope limiter for p-adaptive discontinuous Galerkin methods. J. of Comp. and Appl. Math., 2010.

Initial solution on $x \in [0, 1]$

- $u_0(x) = \sin(2\pi x)$
- Periodic boundary conditions

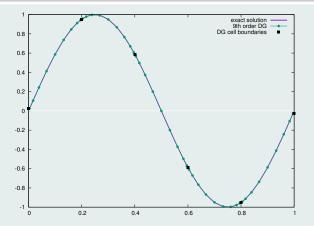


Figure: Linear advection with a 9th DG scheme and 5 cells after 1 period

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Convergence rates

	L ₁		L ₂	
h	$E_{L_1}^h$	$q_{L_1}^h$	$E_{L_2}^h$	$q_{L_2}^h$
1 20	8.07E-11	9.00	8.97E-11	9.00
$\frac{1}{40}$	1.58E-13	9.00	1.75E-13	9.00
<u>1</u>	3.08E-16	-	3.42E-16	-

Table: Convergence rates for the linear advection case for a 9th order DG scheme

Linear advection of a square signal after 1 period

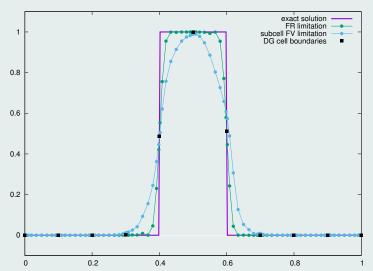


Figure : Comparison between flux reconstruction limitation and subcell finite volume limitation

Linear advection of a square signal after 10 periods

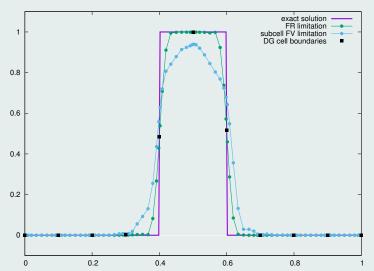


Figure : Comparison between flux reconstruction limitation and subcell finite volume limitation

Linear advection of a square signal after 50 periods

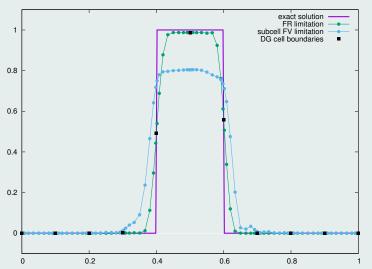


Figure : Comparison between flux reconstruction limitation and subcell finite volume limitation

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Initial solution on $(x, y) \in [0, 1]^2$

- $u_0(x, y) = \sin(2\pi(x + y))$
- Periodic boundary conditions

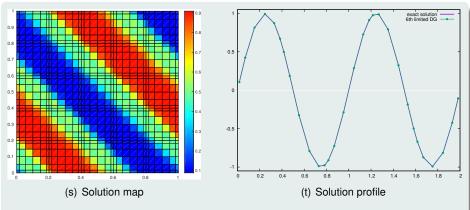


Figure: Linear advection with a 6th DG scheme and 5x5 grid after 1 period

Convergence rates

	L ₁		L ₂	
h	$E_{L_1}^h$	$q_{L_1}^h$	$E_{L_2}^h$	$q_{L_2}^h$
1 5	2.10E-6	6.23	2.86E-6	6.24
1/10	2.79E-8	6.00	3.77E-8	6.00
$\frac{1}{20}$	3.36E-10	-	5.91E-10	-

Table: Convergence rates for the linear advection case for a 6th order DG scheme

Initial solution on $x \in [0, 1]$ for $\gamma = 3$

- $\rho_0(x) = 1 + 0.9999999 \sin(\pi x), \quad u_0(x) = 0, \quad p_0(x) = (\rho_0(x))^{\gamma}$
- Periodic boundary conditions

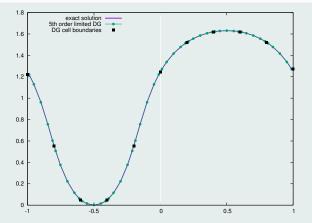


Figure : Smooth flow problem with 5th DG scheme and 10 cells at t = 0.1

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Convergence rates

	L ₁		L ₂	
h	$E_{L_1}^h$	$q_{L_1}^h$	$E_{L_2}^h$	$q_{L_2}^h$
$\frac{1}{20}$	1.48E-5	4.35	2.02E-5	4.18
$\frac{1}{40}$	9.09E-7	4.88	1.38E-6	4.87
<u>1</u>	3.09E-8	4.95	4.73E-8	4.86
1 160	1.00E-9	-	1.63E-9	-

Table: Convergence rates on the pressure for the Euler equation for a 5th order DG

Double rarefaction problem

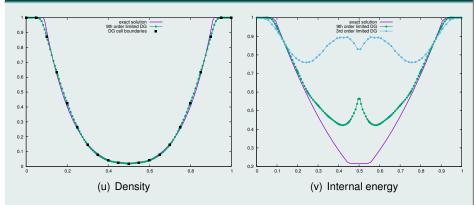


Figure: 9th order limited DG on 20 cells

Leblanc shock tube problem

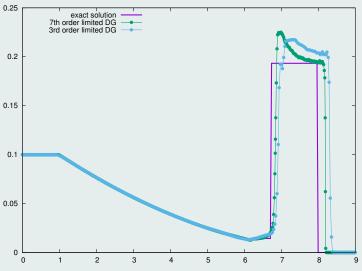


Figure: 3rd order vs 7th order limited DG on 100 cells

Shock acoustic-wave interaction problem

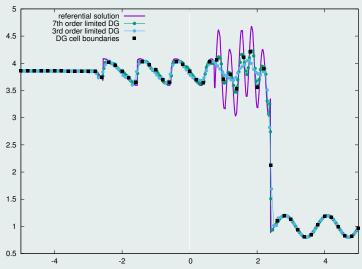


Figure: 3rd order vs 7th order limited DG on 50 cells

Shock acoustic-wave interaction problem

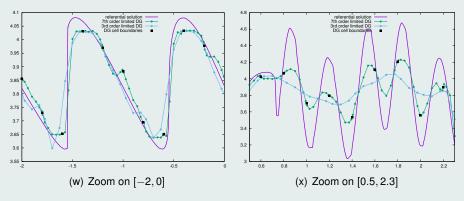


Figure: 3rd order vs 7th order limited DG on 50 cells