Monolithic local subcell DG/FV convex property preserving scheme: entropy consideration

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Monolithic local subcell DG/FV scheme



- 2 DG as a subcell Finite Volume
- Monolithic subcell DG/FV scheme

Scalar conservation law

• $\partial_t u(\mathbf{x}, t) + \nabla_x \cdot \mathbf{F}(u(\mathbf{x}, t)) = 0, \quad (\mathbf{x}, t) \in \omega \times [0, T]$

•
$$u(\mathbf{x}, \mathbf{0}) = u_{\mathbf{0}}(\mathbf{x}),$$
 $\mathbf{x} \in \omega$

$(k+1)^{\text{th}}$ order semi-discretization

- $\{\omega_c\}_c$ a partition of ω , such that $\omega = \bigcup_c \omega_c$
- $u_h(\mathbf{x}, t)$ the numerical solution, such that $u_{h|\omega_c} = u_h^c \in \mathbb{P}^k(\omega_c)$

$$u_h^c(\mathbf{x},t) = \sum_{m=1}^{N_k} u_m^c(t) \, \sigma_m^c(\mathbf{x})$$

•
$$\{\sigma_m^c\}_{m=1,...,N_k}$$
 a basis of $\mathbb{P}^k(\omega_c)$, with $N_k = \frac{(k+1)(k+2)}{2}$ in 2D.

Local variational formulation on ω_c

•
$$\int_{\omega_c} \frac{\partial u_h^c}{\partial t} \psi \, \mathrm{d} V = \int_{\omega_c} \mathbf{F}(u_h^c) \cdot \nabla_x \psi \, \mathrm{d} V - \int_{\partial \omega_c} \psi \, \mathcal{F}_n \, \mathrm{d} S,$$

 $\forall \psi \in \mathbb{P}^k(\omega_c)$

• $\mathcal{F}_n = \mathcal{F}\left(u_h^c, u_h^v, \mathbf{n}\right)$

Solid body rotation: discontinuous Galerkin scheme



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Spurious oscillations, aliasing and non-entropic behavior



Admissible numerical solution

- Maximum principle / positivity preserving
- Ensure a correct entropic behavior

Spurious oscillations

- Discrete maximum principle
- Relaxing condition for smooth extrema

Methodology

Blend, at the subcell scale, high-order DG and 1st-order FV

- **F. VILAR**, A Posteriori Correction of High-Order DG Scheme through Subcell Finite Volume Formulation and Flux Reconstruction. JCP, 2018.
- **F. VILAR** AND **R. ABGRALL**, *A posteriori local subcell correction of DG schemes through Finite Volume reformulation on unstructured grids.* SIAM Sci. Comp., 2023.

Introduction



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DG as a subcell Finite Volume

Rewrite DG scheme as a FV-like scheme on a subgrid

Cell subdivision into $N_S \ge N_k$ subcells







Figure : Examples of $N_s = N_k$ subdivision for \mathbb{P}^3 DG scheme on a triangle



Figure : Examples of $N_S \ge N_k$ subdivision

Monolithic local subcell DG/FV scheme

DG schemes through residuals

•
$$(U_c)_m = u_m^c$$
 Solution moments
• $(M_c)_{mp} = \int_{\omega_c} \sigma_m \sigma_p \, \mathrm{d}V$ Mass matrix
• $(\Phi_c)_m = \int_{\omega_c} \mathbf{F}(u_h^c) \cdot \nabla_x \sigma_m \, \mathrm{d}V - \int_{\partial \omega_c} \sigma_m \, \mathcal{F}_n \, \mathrm{d}S$ DG residuals

Subdivision and definition

• ω_c is subdivided into N_s subcells S_m^c

• Let us define
$$\overline{\psi}_m^c = \frac{1}{|S_m^c|} \int_{S_m^c} \psi \, \mathrm{d}V$$
 the subcell mean value

Submean values

•
$$\overline{u}_{m}^{c} = \frac{1}{|S_{m}^{c}|} \sum_{q=1}^{N_{k}} u_{q}^{c} \int_{S_{m}^{c}} \sigma_{q} \, \mathrm{d}V \implies \overline{U_{c} = P_{c} U_{c}}$$

• $(\overline{U}_{c})_{m} = \overline{u}_{m}^{c}$ Submean values
• $(P_{c})_{mp} = \frac{1}{|S_{m}^{c}|} \int_{S_{m}^{c}} \sigma_{p} \, \mathrm{d}V$ Projection matrix
 $\implies \qquad \boxed{\frac{\mathrm{d} \overline{U}_{c}}{\mathrm{d} t} = P_{c} M_{c}^{-1} \Phi_{c}}$
Admissibility of the cell sub-partition into subcells
• $P_{c}^{t} P_{c}$ has to be non-singular
 $\implies \qquad \boxed{U_{c} = (P_{c}^{t} P_{c})^{-1} P_{c}^{t} \overline{U}_{c}}$ Least square procedure
• If $N_{s} = N_{k}, \ \overline{U}_{c} = P_{c} U_{c} \iff U_{c} = P_{c}^{-1} \overline{U}_{c}$

Subcell Finite Volume: reconstructed fluxes

Let us introduce the reconstructed fluxes such that

$$\frac{\mathrm{d}\,\overline{u}_{m}^{c}}{\mathrm{d}t} = -\frac{1}{|S_{m}^{c}|} \sum_{S_{p}^{v} \in \mathcal{V}_{m}^{c}} \widehat{F_{pm}}$$

- \$\mathcal{V}_m^c\$ is the set of face neighboring subcells of \$S_m^c\$
- We impose that on the boundary of cell ω_c , so for $S_p^{\nu} \notin \omega_c$

$$\widehat{\textit{F}_{\textit{pm}}} = \int_{\textit{f}_{\textit{mp}}^{c}} \mathcal{F}_{\textit{n}} \, \mathrm{d}\textit{S} \equiv \int_{\textit{f}_{\textit{mp}}^{c}} \mathcal{F}\left(\textit{u}_{\textit{h}}^{\textit{c}}, \, \textit{u}_{\textit{h}}^{\textit{v}}, \, \textit{n}_{\textit{mp}}^{\textit{c}}\right) \, \mathrm{d}\textit{S}$$

Let \$\hat{F_c}\$ be the vector containing all the interior faces reconstructed fluxes
Then, \$\hat{F_c}\$ is uniquely defined as following

$$\widehat{F_c} = -A_c^{\mathrm{t}} \, \mathcal{L}_c^{-1} \left(D_c \, P_c \, M_c^{-1} \, \Phi_c + B_c \right)$$

• The only terms depending on the time are Φ_c and B_c

Different cell subdivisions



Figure : Examples of easily generalizable subdivisions for a triangle cell

DG is DG

- Only the functional space matters
- The cell subdivision has no influence on the resulting scheme
- Even in the case where $N_s > N_k$

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Rotation of a composite signal after one full rotation



Rotation of a composite signal after one full rotation



Rotation of a composite signal after one full rotation



Figure : Reconstructed flux FV schemes on 576 cells: solution profiles for y = 0.75

Introduction

- 2) DG as a subcell Finite Volume
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Formulation



Questions regarding entropy

• Can we find the $\theta^i_{m+\frac{1}{2}}$ coefficients ensuring an entropy inequality?

What do we mean by entropy inequality?

- for one or any entropy?
- at the discrete or semi-discrete time level?
- at the cells or subcells space level?

If we manage to ensure an entropy inequality, is it worth the effort?

- in terms of accuracy
- in terms of other critical properties to ensure, as positivity for instance
- Do we really need an entropy inequality to practically capture the entropic weak solution?
- If numerical diffusion is the key, how much do we need?

Definitions

- (η, φ)
- $v(u) = \eta'(u)$

• $\psi(u) = v(u) F(u) - \phi(u)$

entropy - entropy flux entropy variable

entropy potential flux

for all (η, ϕ)

•
$$\phi^*(u^-, u^+) = \frac{\phi(u^-) + \phi(u^+)}{2} - \frac{\gamma}{2} (\eta(u^+) - \eta(u^-))$$

• $\eta(u^*) \le \eta^* := \frac{\eta(u^-) + \eta(u^+)}{2} - \frac{\phi(u^+) - \phi(u^-)}{2\gamma}$

Subcell entropy stability at the discrete level

• if
$$\Delta F_{m+\frac{1}{2}}$$
. $(\overline{u}_{m+1} - \overline{u}_m) > 0$,

$$\theta_{m+\frac{1}{2}} \leq \min\left(1, \frac{\left(\gamma_{m+\frac{1}{2}} - \gamma_{\text{God}}\right)\left(\overline{u}_{m+1} - \overline{u}_{m}\right)}{2\,\Delta F_{m+\frac{1}{2}}}\right)$$

• γ_{God} Godunov viscosity coefficient

⇒ 1st order scheme!

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Semi-discrete subcell entropy dissipation

• if
$$\Delta F_{m+\frac{1}{2}} \cdot \left(v(\overline{u}_{m+1}) - v(\overline{u}_m) \right) > 0$$
,

$$\theta_{m+\frac{1}{2}} \leq \min\left(1, \frac{\frac{\psi(\overline{u}_{m+1}) - \psi(\overline{u}_{m})}{v(\overline{u}_{m+1}) - (\overline{u}_{m})} - \mathcal{F}_{m+\frac{1}{2}}^{\mathsf{FV}}}{\Delta \mathcal{F}_{m+\frac{1}{2}}}\right)$$

2nd order scheme!

- **D. KUZMIN** AND **M. QUEZADA DE LUNA**, Algebraic entropy fixes and convex limiting for continuous finite element discretizations of scalar hyperbolic conservation laws. Comp. Math. Appl. Mech. Eng., 2020.
- A. RUEDA-RAMÍREZ, B. BOLM, D. KUZMIN AND G. GASSNER, Monolithic Convex Limiting for Legendre-Gauss-Lobatto Discontinuous Galerkin Spectral Element Methods. Arxiv, 2023.

for a given (η, ϕ)

Histopolation and sub-resolution basis functions

• Let $\{\lambda_m^c\}_m$ be the histopolation basis function such that, for $v_h^c \in \mathbb{P}^k(\omega_c)$

$$\boldsymbol{v}_h^c = \sum_{m=1}^{N_k} \overline{\boldsymbol{v}}_m^c \, \lambda_m^c$$

• Let $\{\varphi_m^c\}_m$ be the sub-resolution basis function such that, $\forall \psi \in \mathbb{P}^k(\omega_c)$

$$\int_{\omega_c} \varphi_m \psi \, \mathrm{d} \, \mathbf{V} = \int_{\mathbf{S}_m^c} \psi \, \mathrm{d} \, \mathbf{V}$$

• Then, given $v_h^c \in \mathbb{P}^k(\omega_c)$, it writes

$$\boldsymbol{v}_h^c = \sum_{m=1}^{N_k} \underline{\boldsymbol{v}}_m^c \, \boldsymbol{\varphi}_m^c$$

Orthogonality property

$$\int_{\omega_c} \lambda_m^c \, \varphi_p^c \, \mathrm{d} \boldsymbol{V} = |\boldsymbol{S}_m^c| \, \delta_{mp}$$

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 $N_s = N_k$

Semi-discrete cell entropy dissipation

for a given
$$(\eta,\phi)$$

 $\overline{N_k} = k + 1$

•
$$\frac{\mathrm{d}}{\mathrm{d}t} \oint_{\omega_c} \eta(u_h^c) \,\mathrm{d}V = \oint_{\omega_c} v(u_h^c) \,\partial_t u_h^c \,\mathrm{d}V = \int_{\omega_c} v_h^c \,\partial_t u_h^c \,\mathrm{d}V \equiv \Delta \eta_c$$

•
$$v_h^c = \sum_{m=1}^{m} \underline{v}_m^c \varphi_m^c$$
 L^2 projection of $v(u_h^c)$ onto \mathbb{P}^k

•
$$\Delta \eta_c = \int_{\omega_c} \left(\sum_{m=1}^{N_k} \underline{v}_m^c \varphi_m^c \right) \left(\sum_{m=1}^{N_k} \frac{\mathrm{d} \overline{u}_m^c}{\mathrm{d} t} \lambda_m^c \right) \, \mathrm{d} V = \sum_{m=1}^{N_k} |S_m^c| \, \underline{v}_m^c \, \frac{\mathrm{d} \overline{u}_r^c}{\mathrm{d} t}$$

For sake of simplicity, let us consider 1D

•
$$\Delta \eta_i = -\sum_{m=1}^{k+1} \underline{v}_m^i \left(\widetilde{F_{m+\frac{1}{2}}} - \widetilde{F_{m-\frac{1}{2}}} \right) = \mathbf{A}_{vol} + \mathbf{A}_{bdr}$$

• $\mathbf{A}_{vol} = \sum_{m=1}^{k+1} \left(\underline{v}_{m+1}^i - \underline{v}_m^i \right) \widetilde{F_{m+\frac{1}{2}}} + \left(\underline{v}_1^i - v(u_h^i(x_{i-\frac{1}{2}})) \right) \theta_{\frac{1}{2}}^i \widetilde{F_{\frac{1}{2}}^i} + \left(v(u_h^i(x_{i+\frac{1}{2}})) - \underline{v}_{k+1}^i \right) \theta_{k+\frac{3}{2}}^i \widetilde{F_{k+\frac{3}{2}}^i}$

N₁.

Boundary entropy contribution

•
$$\mathcal{F}_{i-\frac{1}{2}}^{\text{FV}} \equiv \mathcal{F}_{\frac{1}{2}}^{i, \text{FV}}, \quad \mathcal{F}_{i+\frac{1}{2}}^{\text{FV}} \equiv \mathcal{F}_{k+\frac{3}{2}}^{i, \text{FV}}, \quad \mathcal{F}_{i-\frac{1}{2}}^{\text{DG}} \equiv \widehat{F}_{\frac{1}{2}}^{i}, \quad \mathcal{F}_{i+\frac{1}{2}}^{\text{DG}} \equiv \widehat{F}_{k+\frac{3}{2}}^{i}$$

• $\theta_{i+\frac{1}{2}} \equiv \theta_{k+\frac{3}{2}}^{i} = \theta_{\frac{1}{2}}^{i+1} \quad \bullet \quad \mathbf{v}_{\frac{1}{2}\pm\frac{1}{2}}^{\mp} \equiv \mathbf{v} \left(u_{h}^{i}(\mathbf{x}_{i\pm\frac{1}{2}}) \right)$
• $\mathbf{A}_{bdr} = \underline{v}_{1}^{i} \left(1 - \theta_{i-\frac{1}{2}} \right) \mathcal{F}_{i-\frac{1}{2}}^{\text{FV}} + \mathbf{v}_{i-\frac{1}{2}}^{+} \theta_{i-\frac{1}{2}} \mathcal{F}_{i-\frac{1}{2}}^{\text{DG}}$
 $-\underline{v}_{k+1}^{i} \left(1 - \theta_{i+\frac{1}{2}} \right) \mathcal{F}_{i+\frac{1}{2}}^{\text{FV}} - \mathbf{v}_{i+\frac{1}{2}}^{-} \theta_{i+\frac{1}{2}} \mathcal{F}_{i+\frac{1}{2}}^{\text{DG}}$

Semi-discrete cell entropy stability

• $\mathcal{F}_{m+\frac{1}{2}}^{FV} := \mathcal{F}(u(\underline{v}_{m+1}), u(\underline{v}_{m}))$

for a given (η, ϕ)

modified FV numerical flux

A sufficient condition to entropy stability writes as follows

$$\mathbf{A}_{\textit{vol}} \leq \theta_{i-\frac{1}{2}} \Big(\psi(\underline{v}_{1}^{i}) - \psi(v_{i-\frac{1}{2}}^{+}) \Big) + \theta_{i+\frac{1}{2}} \left(\psi(v_{i+\frac{1}{2}}^{-}) - \psi(\underline{v}_{k+1}^{i}) \right) + \psi(\underline{v}_{k+1}^{i}) - \psi(\underline{v}_{1}^{i}) \Big)$$

Y. LIN AND **J. CHAN**, *High order entropy stable discontinuous Galerkin spectral element methods through subcell limiting.* JCP, 2024.

Proof

•
$$\Delta \eta_i \leq \left(\mathbf{1} - \theta_{i-\frac{1}{2}} \right) \left(\underline{\underline{v}}_1^i \, \mathcal{F}_{i-\frac{1}{2}}^{\mathsf{FV}} - \psi(\underline{\underline{v}}_1^i) \right) + \theta_{i-\frac{1}{2}} \left(\mathbf{v}_{i-\frac{1}{2}}^+ \, \mathcal{F}_{i-\frac{1}{2}}^{\mathsf{DG}} - \psi(\mathbf{v}_{i-\frac{1}{2}}^+) \right) \\ - \left(\mathbf{1} - \theta_{i+\frac{1}{2}} \right) \left(\underline{\underline{v}}_{k+1}^i \, \mathcal{F}_{i+\frac{1}{2}}^{\mathsf{FV}} - \psi(\underline{\underline{v}}_{k+1}^i) \right) - \theta_{i+\frac{1}{2}} \left(\mathbf{v}_{i+\frac{1}{2}}^- \, \mathcal{F}_{i+\frac{1}{2}}^{\mathsf{DG}} - \psi(\mathbf{v}_{i+\frac{1}{2}}^-) \right)$$

• Given (v_L, v_R) , if $\exists D \ge 0$ such that

$$\mathcal{F}(u(v_L), u(v_R)) = \frac{\psi(v_R) - \psi(v_L)}{v_R - v_L} - \frac{\mathsf{D}}{\mathsf{2}} (v_R - v_L)$$

then

$$\frac{\mathrm{d}}{\mathrm{d}t}\oint_{\omega_i}\eta(u_h^i)\;\mathrm{d}V\leq-\left(\widetilde{\phi_{i+\frac{1}{2}}}-\widetilde{\phi_{i-\frac{1}{2}}}\right)$$

•
$$\widetilde{\phi_{i+\frac{1}{2}}} = \left(1 - \theta_{i+\frac{1}{2}}\right) \phi^* \left(\underline{v}_{k+1}^i, \underline{v}_1^{i+1}\right) + \theta_{i+\frac{1}{2}} \phi^* \left(v_{i+\frac{1}{2}}^-, v_{i+\frac{1}{2}}^+\right)$$

• $\phi^* (v_L, v_R) = \frac{v_L + v_R}{2} \mathcal{F} \left(u(v_L), u(v_R)\right) - \frac{\psi(v_L) + \psi(v_R)}{2}$

Knapsack problem

• The sufficient condition rewrites as

$$oldsymbol{a}$$
 . $oldsymbol{\Theta} \leq oldsymbol{b}$

•
$$\boldsymbol{\Theta} = \left(\theta_{\frac{1}{2}}^{i}, \dots, \theta_{k+\frac{3}{2}}^{i}\right)^{t}$$

• $\boldsymbol{a} = \left(a_{\frac{1}{2}}^{i}, \dots, a_{k+\frac{3}{2}}^{i}\right)^{t}$ defined as

$$\begin{cases} a_{\frac{1}{2}} = \left(\underline{v}_{1}^{i} - v_{i-\frac{1}{2}}^{+}\right) \mathcal{F}_{i-\frac{1}{2}}^{\mathsf{DG}} - \left(\psi(\underline{v}_{1}^{i}) - \psi(v_{i-\frac{1}{2}}^{+})\right), \\ a_{m+\frac{1}{2}} = \left(\underline{v}_{m+1}^{i} - \underline{v}_{m}^{i}\right) \left(\widehat{F_{m+\frac{1}{2}}} - \mathcal{F}_{m+\frac{1}{2}}^{\mathsf{FV}}\right), \qquad m \in [\![1, k]\!] \\ a_{k+\frac{3}{2}} = \left(v_{i+\frac{1}{2}}^{-} - \underline{v}_{k+1}^{i}\right) \mathcal{F}_{i+\frac{1}{2}}^{\mathsf{DG}} - \left(\psi(v_{i+\frac{1}{2}}^{-}) - \psi(\underline{v}_{k+1}^{i})\right), \end{cases}$$

•
$$b = \psi(\underline{v}_{k+1}^{i}) - \psi(\underline{v}_{1}^{i}) - \sum_{m=1}^{k+1} (\underline{v}_{m+1}^{i} - \underline{v}_{m}^{i}) \mathcal{F}_{m+\frac{1}{2}}^{FV}$$

• Because $b \ge 0$ the Knapsack problem is indeed solvable

Greedy algorithm

• Find
$$\mathbf{0} \leq \mathbf{\Theta} \leq \mathbf{\Theta}_{C} \leq \mathbf{1}$$
 maximizing $\sum_{m=1}^{k+1} \theta_{m+\frac{1}{2}}$ such that

$$oldsymbol{a}$$
 . $oldsymbol{\Theta} \leq b$

•
$$\Theta_C = \left(\theta_{\frac{1}{2}}^C, \ldots, \theta_{k+\frac{3}{2}}^C\right)^{\iota}$$
 is a given supplementary constraint

High-order accuracy preservation

- Let us consider *u* a smooth exact solution
- $u_h^i = u + O(\Delta x^{k+1})$ $(k+1)^{\text{th}}$ -order approximation
- Then, we have that

a.1
$$-b=O(\Delta x^{k+2})$$

This implies that

$$\widetilde{F_{m+\frac{1}{2}}^{i}} = F(u(x_{m+\frac{1}{2}}^{i})) + O(\Delta x^{k+1})$$

Linear advection of a composite signal



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 $\eta(\mathbf{u}) = \frac{1}{2}\mathbf{u}^2$

Linear advection of a composite signal $\eta(u) = |u - k_e|^{1+\epsilon} \setminus (1+\epsilon)$



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Linear advection of a composite signal $\eta(u) = |u - k_e|^{1+\epsilon} \setminus (1+\epsilon)$



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KPP non-convex flux problem

 $\eta(\mathbf{U}) = \frac{1}{2}\mathbf{U}^2$



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Questions regarding entropy \longrightarrow pieces of answer

• Can we find $\theta^i_{m+\frac{1}{2}}$ coefficients ensuring an entropy inequality?



What do we mean by entropy inequality, and is it worth the effort?

• for any entropy, at the discrete time level and for any subcell

\hookrightarrow 1st-order

• for a given entropy, at the semi-discrete time level for any subcells

\hookrightarrow 2nd-order

• for a given entropy, at the semi-discrete time level for any cells

$$\begin{array}{ccc} \hookrightarrow & (k+1)^{\text{th-order}} \\ \hookrightarrow & \mathcal{F}_{m+\frac{1}{2}}^{\text{FV}} := \mathcal{F}(u(\underline{v}_{m+1}), u(\underline{v}_m)) \end{array}$$

• Do we need entropy stability or just "enough" numerical diffusion?

 \rightarrow Unclear... \Rightarrow GMP and LMP + relaxation

Global maximum principle

$$\theta_{m+\frac{1}{2}} \leq \min\left(\mathbf{1}, \left|\underbrace{\frac{\gamma_{m+\frac{1}{2}}}{\Delta F_{m+\frac{1}{2}}}}_{D_{m+\frac{1}{2}}}\right| \min\left(\beta - u_{m+\frac{1}{2}}^*, u_{m+\frac{1}{2}}^* - \alpha\right)\right)$$

Local maximum principle

$$\overline{u}_m^{n+1} \in \mathrm{I}\left(\overline{u}_{m-1}^n, \, \overline{u}_m^n, \, \overline{u}_{m+1}^n\right)$$

 \overline{u}_m^{n+1}

 $\in [\alpha, \beta]$

•
$$\widetilde{u_{m+\frac{1}{2}}}^{-} \in [\alpha_m, \beta_m] := \mathrm{I}\left(\overline{u}_{m-1}^n, \overline{u}_m^n, \overline{u}_{m+1}^n\right)$$

•
$$\widetilde{\mathcal{U}_{m+\frac{1}{2}}}^+ \in [\alpha_{m+1}, \beta_{m+1}] := \mathrm{I}\left(\overline{\mathcal{U}_m^n}, \overline{\mathcal{U}_{m+1}^n}, \overline{\mathcal{U}_{m+2}^n}\right)$$

$$\theta_{m+\frac{1}{2}} \le \min\left(1, \left| D_{m+\frac{1}{2}} \right| \left\{ \begin{array}{l} \min\left(\beta_{m+1} - u_{m+\frac{1}{2}}^{*}, u_{m+\frac{1}{2}}^{*} - \alpha_{m}\right) & \text{if } \Delta F_{m+\frac{1}{2}} > 0\\ \min\left(\beta_{m} - u_{m+\frac{1}{2}}^{*}, u_{m+\frac{1}{2}}^{*} - \alpha_{m+1}\right) & \text{if } \Delta F_{m+\frac{1}{2}} < 0 \end{array} \right)$$

Smooth extrema relaxation to preserve accuracy

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Monolithic local subcell DG/FV scheme

Linear advection of a composite signal



Linear advection of a composite signal





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$u_0(x,y) = \sin(2\pi \left(x+y\right))$

(a) Solution submean values

(b) Blending coefficients

Figure : ℙ⁵-DG/FV scheme with GMP and relaxed-LMP on 242 cells

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Burgers equation

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KPP non-convex flux problem



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Non-linear Euler compressible gas dynamics equations

•
$$\partial_t \mathbf{V} + \nabla_x \cdot \mathbf{F}(\mathbf{V}) = \mathbf{0}$$

• $\mathbf{V} = \begin{pmatrix} \rho \\ \mathbf{q} \\ E \end{pmatrix}$ conservative variables
• $\mathbf{F}(\mathbf{V}) = \begin{pmatrix} \mathbf{q} \otimes \mathbf{q} \\ \rho \\ \rho \\ (E+p) \frac{\mathbf{q}}{\rho} \end{pmatrix}$ flux function
• $p := p(\mathbf{V}) = (\gamma - 1) \left(E - \frac{1}{2} \frac{\||\mathbf{q}\||^2}{\rho} \right)$ equation of state
Monolithic subcell DG/FV scheme property
• Positivity of the density and internal energy, at the subcell scale

Definitions

Monolithic local subcell DG/FV scheme

Positivity of the internal energy

•
$$A_{m+\frac{1}{2}} = \frac{1}{(\gamma_{m+\frac{1}{2}})^2} \left(\frac{1}{2} \left(\Delta F_{m+\frac{1}{2}}^q \right)^2 - \theta_{m+\frac{1}{2}}^{\rho(1)} \Delta F_{m+\frac{1}{2}}^\rho \Delta F_{m+\frac{1}{2}}^E \right)$$

• $B_{m+\frac{1}{2}} = \frac{1}{\gamma_{m+\frac{1}{2}}} \left(q_{m+\frac{1}{2}}^* \Delta F_{m+\frac{1}{2}}^q - \rho_{m+\frac{1}{2}}^* \Delta F_{m+\frac{1}{2}}^E - \theta_{m+\frac{1}{2}}^{\rho(1)} E_{m+\frac{1}{2}}^* \Delta F_{m+\frac{1}{2}}^\rho \right)$
• $M_{m+\frac{1}{2}} = \rho_{m+\frac{1}{2}}^* E_{m+\frac{1}{2}}^* - \frac{1}{2} \left(q_{m+\frac{1}{2}}^* \right)^2$

$$heta_{m+rac{1}{2}}^{(2)} \le \min\left(1, \, rac{M_{m+rac{1}{2}}}{\left|B_{m+rac{1}{2}}\right| + \max\left(0, A_{m+rac{1}{2}}
ight)}
ight)$$

•
$$\theta_{m+\frac{1}{2}}^{\rho} = \theta_{m+\frac{1}{2}}^{\rho(1)} \theta_{m+\frac{1}{2}}^{(2)}, \quad \theta_{m+\frac{1}{2}}^{q} = \theta_{m+\frac{1}{2}}^{(2)}, \quad \theta_{m+\frac{1}{2}}^{E} = \theta_{m+\frac{1}{2}}^{(2)}$$

A. RUEDA-RAMÍREZ, B. BOLM, D. KUZMIN AND G. GASSNER, Monolithic Convex Limiting for Legendre-Gauss-Lobatto Discontinuous Galerkin Spectral Element Methods. Arxiv, 2023.

LMP

$$\overset{n+1}{m} \in \mathrm{I}\left(\overline{v}_{m-1}^{n}, \, v_{m-\frac{1}{2}}^{*}, \, \overline{v}_{m}^{n}, \, v_{m+\frac{1}{2}}^{*}, \, \overline{v}_{m+1}^{n}\right)$$

• $v \in \{\rho, q, E\}$

conservative variable

•
$$\widetilde{\mathbf{v}_{m+\frac{1}{2}}}^{-} \in [\alpha_m, \beta_m] := \mathrm{I}\left(\overline{\mathbf{v}_{m-1}^n}, \mathbf{v}_{m-\frac{1}{2}}^*, \overline{\mathbf{v}}_m^n, \mathbf{v}_{m+\frac{1}{2}}^*, \overline{\mathbf{v}}_{m+1}^n\right)$$

• $\widetilde{\mathbf{v}_{m+\frac{1}{2}}}^{+} \in [\alpha_{m+1}, \beta_{m+1}] := \mathrm{I}\left(\overline{\mathbf{v}}_m^n, \mathbf{v}_{m+\frac{1}{2}}^*, \overline{\mathbf{v}}_{m+1}^n, \mathbf{v}_{m+\frac{3}{2}}^*, \overline{\mathbf{v}}_{m+2}^n\right)$

$$\theta_{m+\frac{1}{2}} \le \min\left(1, \left| D_{m+\frac{1}{2}} \right| \begin{cases} \min\left(\beta_{m+1} - v_{m+\frac{1}{2}}^{*}, v_{m+\frac{1}{2}}^{*} - \alpha_{m}\right) & \text{if } \Delta F_{m+\frac{1}{2}} > 0 \\ \min\left(\beta_{m} - v_{m+\frac{1}{2}}^{*}, v_{m+\frac{1}{2}}^{*} - \alpha_{m+1}\right) & \text{if } \Delta F_{m+\frac{1}{2}} < 0 \end{cases} \end{cases}$$

Smooth extrema relaxation to preserve accuracy

Entropy inequalities

• The same techniques apply here \implies But is that really needed?

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Sod shock tube test case





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Double rarefaction test case



Shock acoustic-wave interaction test case



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Smooth isentropic solution



Table: Convergence rates computed on the pressure with a 5th-order DG/FV scheme

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 $\rho_0 = 1 + 0.9999999 \sin(2\pi x)$

Sod shock tube problem in cylindrical geometry



(a) Density map

Figure : 6th-order APLSC-DG with GMP and relaxed-LMP on a 110 cells mesh

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Sedov point blast problem in cylindrical geometry



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Monolithic local subcell DG/FV scheme

- Reformulate DG schemes as subgrid FV-like schemes:
 - regardless the type of mesh used
 - regardless the space dimension (*in theory*...)
 - regardless the cell subdivision ($N_s \ge N_k$)
- Combine high-order reconstructed fluxes and 1st-order FV fluxes
 - ensuring a maximum or positivity preserving principle at the subcell scale
 - ensuring different entropy stability inequalities
 - reducing significantly the apparition of spurious oscillations
 - preserving the very accurate subcell resolution of DG schemes

Questions

Is an entropy inequality for one entropy enough?



Is entropy inequality absolutely needed?

 \hookrightarrow

Maybe not \implies GMP + relaxed LMP

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Articles on this topic

- **F. VILAR**, A Posteriori Correction of High-Order DG Scheme through Subcell Finite Volume Formulation and Flux Reconstruction. JCP, 387:245-279, 2018.
 - A. HAIDAR, F. MARCHE AND F. VILAR, A posteriori Finite-Volume local subcell correction of high-order discontinuous Galerkin schemes for the nonlinear shallow-water equations. JCP, 452:110902, 2022.
- **F. VILAR** AND **R. ABGRALL**, A posteriori local subcell correction of DG schemes through Finite Volume reformulation on unstructured grids. SIAM SISC, 46(2), 2024.
- A. HAIDAR, F. MARCHE AND F. VILAR, Free-boundary problems for wave-structure interactions in shallow-water: DG-ALE description and local subcell correction. JSC, 98(45), 2024.
 - **A. HAIDAR, F. MARCHE** AND **F. VILAR**, A robust DG-ALE formulation for nonlinear shallow-water interactions with a floating object. JSC, under review, 2024.

Conclusion?

Linear advection of a composite signal $\eta(u) = |u - k_e|^{1+\epsilon} \setminus (1+\epsilon)$



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